

## Vehicle-Track-Interaction-System 23.11.2016, Dr. T. Moshammer, MO MLT BG EN SSV

Open to Public © Siemens AG 2016

siemens.com/mobility

 $R = f (a_x, a_y, a_z, \omega_x, \omega_y, \omega_y, n, ....)$ 



Dr. Thomas Moshammer: Vehicle-Track-Interaction-System Contents







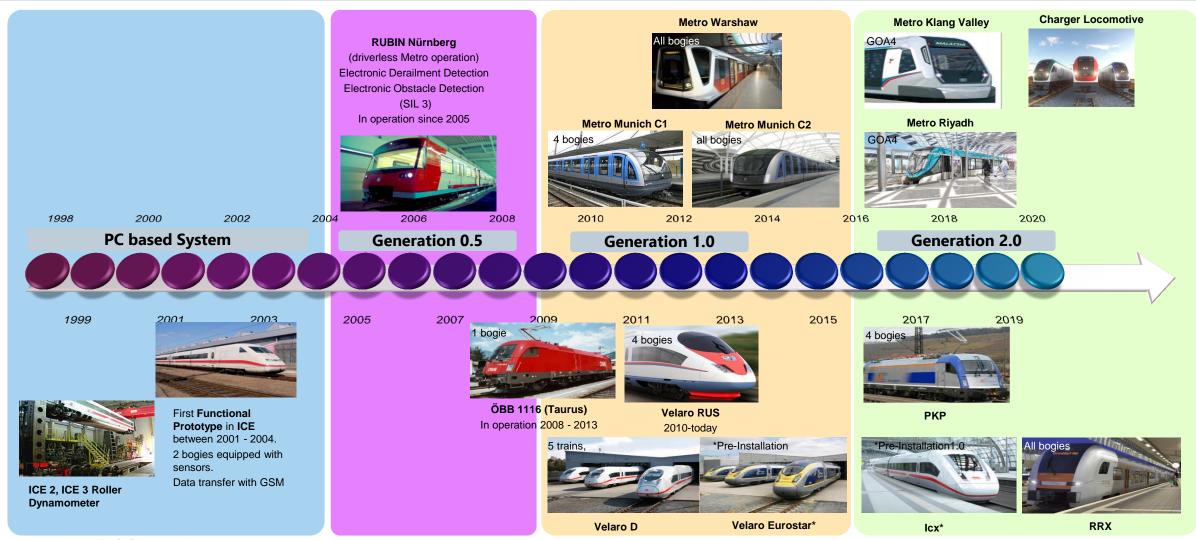
## CONTENTS:

- The history in the development of the SIEMENS Vehicle-Track-Interaction System...
- Why is a Track-Vehicle-Interaction so important?
- What is a Vehicle-Track-Interaction Monitoring System?
- Why might it be interesting to have a Track Monitoring System on a Train?
- What are the restrictions of such a Monitoring System?
- Summary



# There is a long History in Development of Bogie Monitoring & Diagnostics Systems at SIEMENS! We are ready to use this Expertise!

#### **SIEMENS**



Open to Public © Siemens AG 2016

23.11.2016





## Why is the Vehicle-Track-Interaction so important?

## Why is the Vehicle-Track-Interaction so important?

- The vehicle-track system has to be maintained that save operation is possible and guaranteed
- Unsave in this context means high forces, high wheel unloading, high strike angles, high slippage in the wheel-rail contact
- Essential is the wheel-rail-interaction because it determines the height of the interacting terms (forces, slippage, accelerations, etc.)
- That makes measurements of the interaction of vehicle and track essential for maintenance
- Diagnostics of the vehicle track interaction would help to make an accurate prediction of the development of this interaction behavior possible



Open to Public © Siemens AG 2016

Seite 4 23.11.2016





Vehicles are assessed separately...

- **Testing** for the acceptance of running characteristics of railway vehicles according to **EN14363**
- Periodical Maintenance Intervals according to the maintenance handbook
- Visual Inspection of parts
- **Measuring** of wearing parts (e.g. wheel) and crack detection
- Exchange of Components according to the maintenance plan or after measuring
- Test drives after maintenance works





Open to Public © Siemens AG 2016

Seite 5 23.11.2016









... Tracks are assessed separately

- Visual Inspections of tracks
- Observations by the train driver and the train crew
- Measurements of track geometry with track recording cars
- Measuring of wear of the track, switchings, etc.
- Crack detection of components of the track...



#### SIEMENS

Vehicles are assessed separately ...



## Rarely consideration of the interaction between vehicle and track,

## rarely permanent diagnostics

**Open to Public © Siemens AG 2016** 

Seite 7 23.11.2016 Dr. T. Moshammer / MO MLT BG EN SSV



The traditional way of diagnosis of the interaction between train and track shows the opportunity of improvement

#### **SIEMENS**

- The two subsystems vehicle and track are considered stand alone
- Diagnosis is not performed continuously but in periodically defined time schedules
- Not the interaction itself is considered but quantities which are assumed to affect the interaction between vehicle and track
- It would be perfect to have a permanent diagnosis of the interaction between vehicle and track.

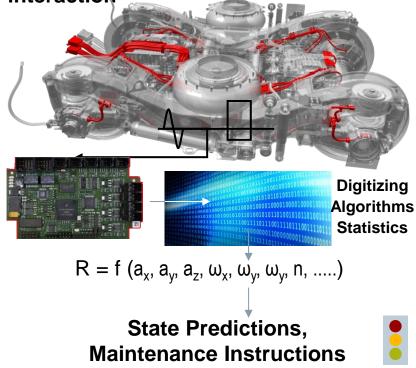




There are several possibilities to diagnose several aspects of the interaction permanently

SIEMENS

The SIEMENS Bogie Diagnostics System (SBDS) is a sensoric system for the identification of the behavior of the system bogie and the vehicle track interaction



<u>"It would be perfect to have a permanent diagnosis of the interaction between vehicle and track."</u>

#### Approach: Bogie Diagnostics and Vehicle Track Interaction System

- Bogies with sensors which measure significant movement quantities and thus capture the impacts of the interaction between vehicle and track.
- With this Vehicle-Track-Interaction-System abnormal behavior is detected.
- Changes in the behavior of bogie components are detected as well.

#### Main benefits:

- Condition-based maintenance of bogies becomes possible.
- Corrective maintenance measures become predictable.
- Components can be used for a longer period (utilization of the individual service life)

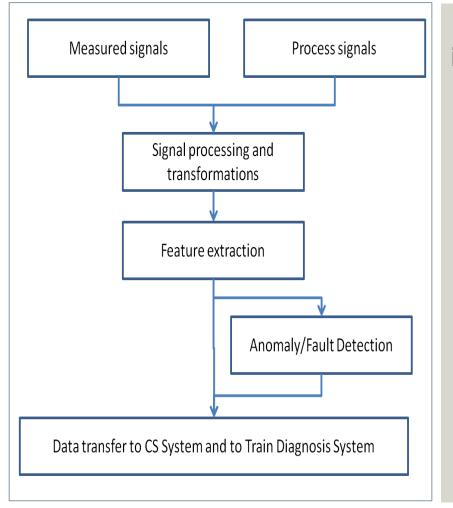
**Side Effect:** Interaction-relevant condition of the driveway is recorded!

#### Open to Public © Siemens AG 2016

Seite 9 23.11.2016



# The development of efficient diagnostics Systems is complex and challenging



In the development of an **effective diagnostics system** a set of **interdisciplinary competences** are necessary:

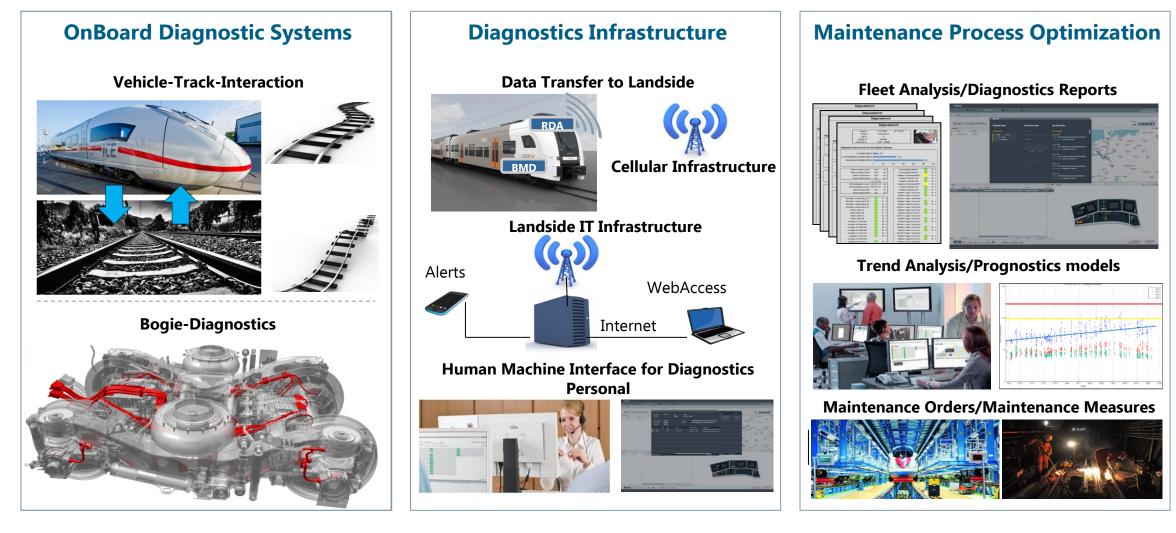
- Development of "rail-operation-resistent" Sensors and Electronics
- Modern methods of signal processing and anomality/fault detection
- Knowledge of the system behavior of rail vehicles
- Knowledge of the operational necessities and technical possibilities for the optimization of maintenance processes

Open to Public © Siemens AG 2016



The way from OnBoard Diagnostics to Maintenance Process Optimization needs a full IT-Integration of the Diagnostic Data in the Maintenance System

**SIEMENS** 





## Siemens Bogie Diagnostics including the Vehicle Track Interaction System provides a wide range of functions

#### SIEMENS



#### SIEMENS Bogie Diagnostics and Vehicle Track Interaction System Functions

BHC Bogie Health Check				
	ID Code	Function		
$\checkmark$	BFP	Bogie Finger Print		
$\checkmark$	RCD	Ride & Comfort Diagnostics		
$\checkmark$	EID	Early Instability Detection		
FOD Field Operation Diagnostics				
	ID Code	Function		
$\checkmark$	FOD	Field Operation Diagnostics		
APF Advanced Prediction Functions				
	ID Code	Function		
$\checkmark$	BWP	Brake Wear Prognostics		
$\checkmark$	WPP	Wheel Profile Prognostics		

**Rubber Lifetime Prognostics** 

Load Cycle Counter

WAD Wheel & Axle Diagnostics				
	ID Code	Function		
$\checkmark$	ABD	Axle Bearing Diagnostics		
$\checkmark$	WD	Wheel Diagnostics		
GMD Gear & Motor Diagnostics				
	ID Code	Function		
$\checkmark$	GBD	Gear Box Diagnostics		
$\checkmark$	MBD	Motor Bearing Diagnostics		
ACD Advanced Component Diagnostics				

	ID Code	Function
$\checkmark$	YDD	Yaw Damper Diagnostics
$\checkmark$	ARDD	Anti Rolling Device Diagnostics
	WSGD	Wheelset Guidance Diagnostics

TSI Supervision					
	ID Code	Function			
$\checkmark$	HBD	Hot Box Detection			
$\checkmark$	WMS	Wheel Monitoring System			
$\checkmark$	URD	Unstable Running Detection			
GOAx Supervision					
	ID Code	Function			
	EDD	Electronic Derailment Detection			
	EOD	Electronic Obstacle Detection			
GID Gravel Impact Detection					
	ID Code	Function			
	GID	Gravel Impact Detection			
TCI Track Condition Indicator					
	ID Code	Function			

Track Condition Indicator

Train Diagnostics System

**Configuration Management System** 

**Bogie Diagnostics Expert System** 

Track Conditon Indication System

TCI

 $\checkmark$ 

 $\checkmark$ 

 $\checkmark$ 

 $\checkmark$ 

Landside Diagnostics systems

ID Code

TDS

CM

BDES

TCIS

#### Siemens Bogie Diagnostics including the Vehicle Track Interaction System provides a wide range of functions

#### **OnBoard and Landside Solutions are needed!**

Open to Public © Siemens AG 2016

Seite 12 23.11.2016

RLP

LoCCo

 $\checkmark$ 

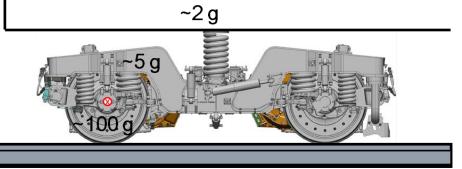


## **5** Categories of Functions have to be distinguished



**3 levels** of acceleration:

- Unsprung masses: The area of the wheelset including the axle bearing box as the contact to the rail is the area of highest impacts to any bogie (~100 g).
- **Primary spring:** The frame and all frame mounted parts still have high accelerations (~5 g).
- Secondary spring: The carbody has low accelerations (~2 g)



Processing the measured data to messages (based on adjustable low/high levels) let the bogie "talk".

#### Diagnosis of Components

- Algorithms detect defects of components
- Examples: Axle Bearing Diagnostics, Wheel Flats, Polygonization of wheels, ...
- Diagnosis of the System Behavior
  - Algorithms analyze the dynamic behavior of the vehicle
  - Examples: Bogie Finger Print, Early Instability Detection, ...
- Prognostic Models
  - The wear influencing and component damaging quantities are measured and with models the remaining service life are estimated.
- Examples: Brake Wear, Wheel Wear, ...
- Vehicle-Track-Interaction Diagnosis
  - Accelerations in 3 Vehicle Levels (unsprung, primary spring, secondary spring level) are recorded and analyzed, high levels are transferred with GPS position to the landside
- Supervision Functions
  - TSI / GOA4 / Gravel Impact Detection

Open to Public © Siemens AG 2016

Seite 13 23.11.2016

SIFMENS



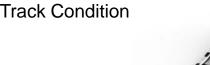
## **US Locomotive: Simple Vehicle Track Interaction System**

#### **SIEMENS**





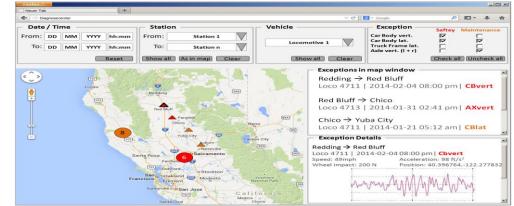




- Sensors
- **BMD** Bogie Monitoring & Diagnostics Electronics
- **RDA** Global Positioning & Data Provider System



#### Landside: Vehicle-Track-Interaction-System



Open to Public © Siemens AG 2016

Seite 14 23.11.2016



Saftey

Position: 40.396764,-122.277832

▼ C<sup>4</sup> 8 + Google

**Exceptions in map window** 

Redding  $\rightarrow$  Red Bluff

Red Bluff  $\rightarrow$  Chico

Chico → Yuba Citv

Exception Details
Redding → Red Bluff

Speed: 49mph

Wheel impact: 200 N

Clear

Exception

Car Body vert.

Car Body lat.

Truck Frame lat.

Axle vert. (I + r)

Loco 4711 | 2014-02-04 08:00 pm | CBvert

Loco 4713 | 2014-01-31 02:41 pm | AXvert

Loco 4711 | 2014-01-21 05:12 am | CBlat

Loco 4711 | 2014-02-04 08:00 pm | Cbvert

Vehicle

Locomotive

Show all

- 0 ×

P 🖸 - 🖡 🌾

Maintenance

5

П

V

Uncheck a



## **US Locomotive Charger: Simple Vehicle Track Interaction System**

### Vehicle-Track-Interaction-System Functions?

- Certain acceleration limits (Level Low / Level High) can be set individually for
  - Car Body vertical
  - Car Body lateral
  - Truck Frame lateral
  - Axle vertical left side
  - Axle vertical right side
- If this limit is reached in one of the positions this is sent to the landside system including additional data (raw data, velocity, GPS position, etc.)
- On the landside system filter functions help to visualize this information on a map or look on certain events.
- Additionally the time history is important to optimize track maintenance efforts

Open to Public © Siemens AG 2016

Seite 15 23.11.2016



+

Station

Station 1

Station r

As in map

From:

To:

Show all

Neuer Tab

< \_>

÷

Date / Time

From: DD MM YYYY hh:mm

To: DD MM YYYY hh:mm

Eureka

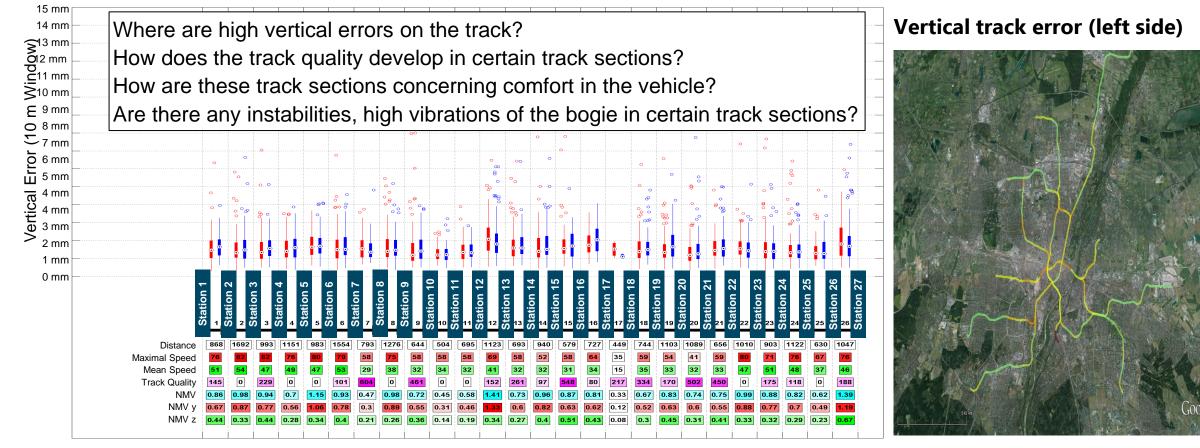
101



Metro Operation: Vertical Error and Statistical Vehicle Values give valuable additional information analyzing the track

**SIEMENS** 

## **Statistical Vehicle Values give Additional Information Analyzing the Track**

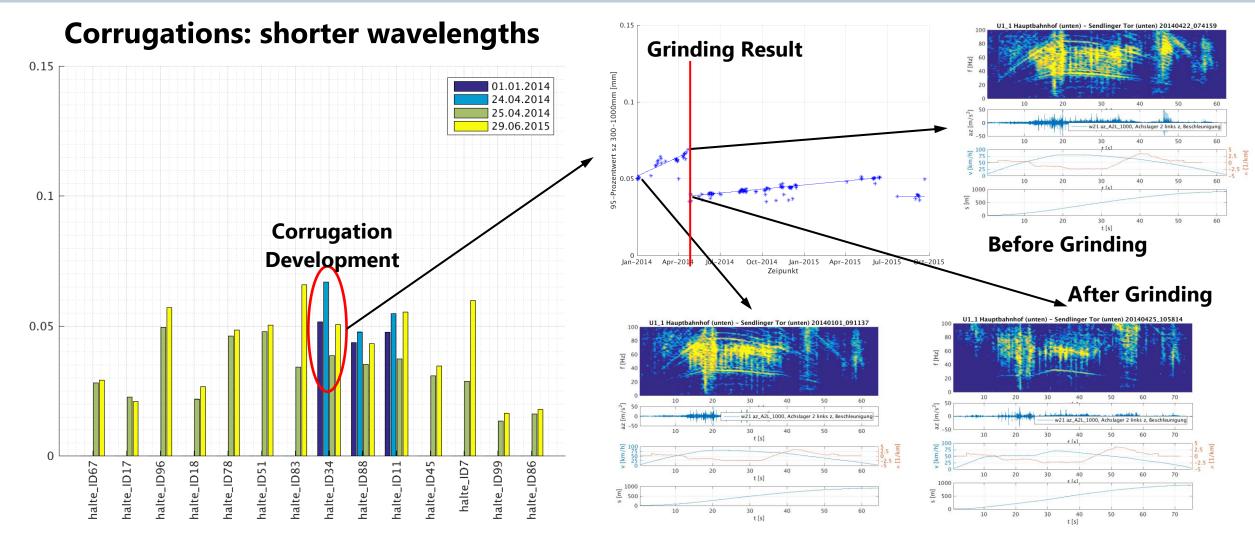


Open to Public © Siemens AG 2016



Metro Operation: Corrugation Characteristics can be determined and Grinding Results are rated

**SIEMENS** 



Open to Public © Siemens AG 2016

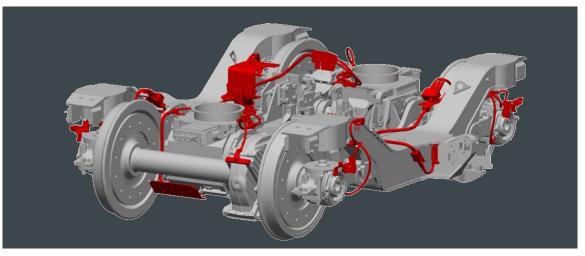
23.11.2016



## Typical Results from Track Analysis:

- The acceleration signals of the axle bearing housing are double integrated and the vertical track error is calculated with this procedure.
- These vertical errors are **analyzed according** to the **Russian chord measurement method** and are **rated** according to normative regulations **concerning track maintenance limits.**
- Visualization of track positions where the maintenance limits are exceeded.



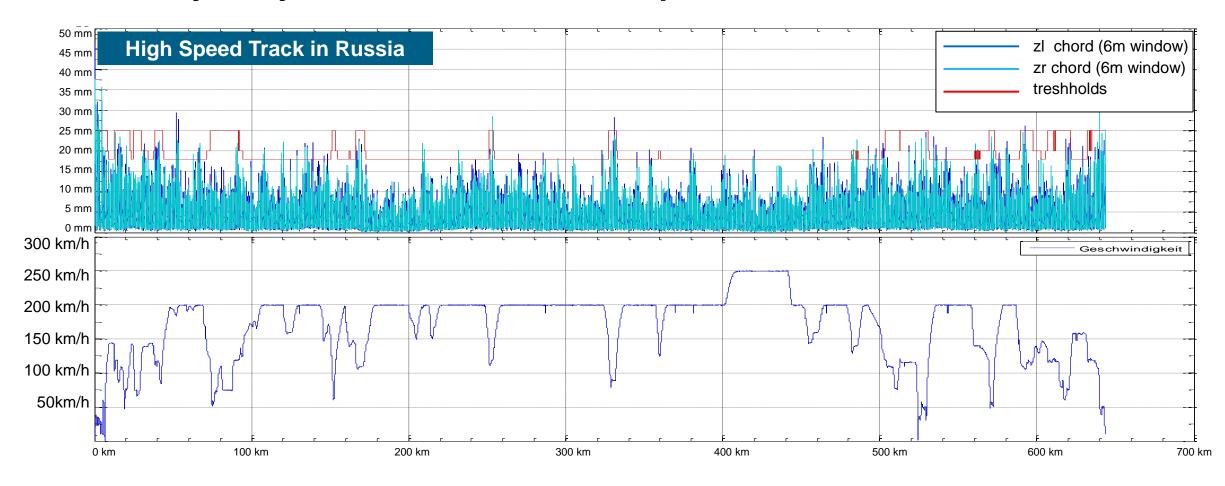






Russian High Speed Train: Track Geometry Analysis according to Russian Track Maintenance Rules (Vertical Error)

## **Track Geometry Analysis: Vertical Error on a Sleeper Track**



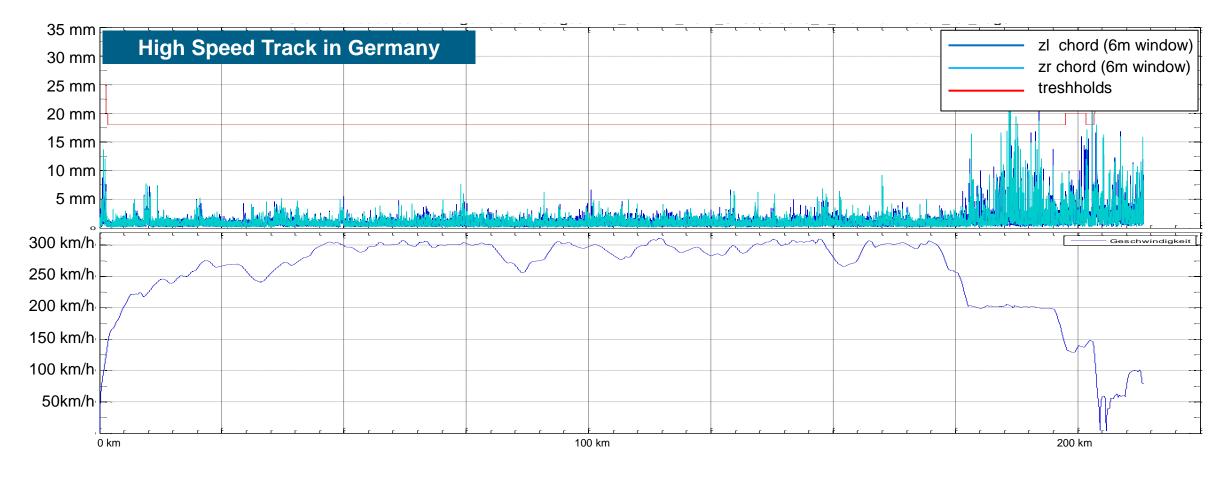
Open to Public © Siemens AG 2016

Seite 19 23.11.2016



German High Speed Train: Track Geometry Analysis according to Russian Track Maintenance Rules (Vertical Error)

## **Track Geometry Analysis: Vertical Error on a Slab Track**



Open to Public © Siemens AG 2016

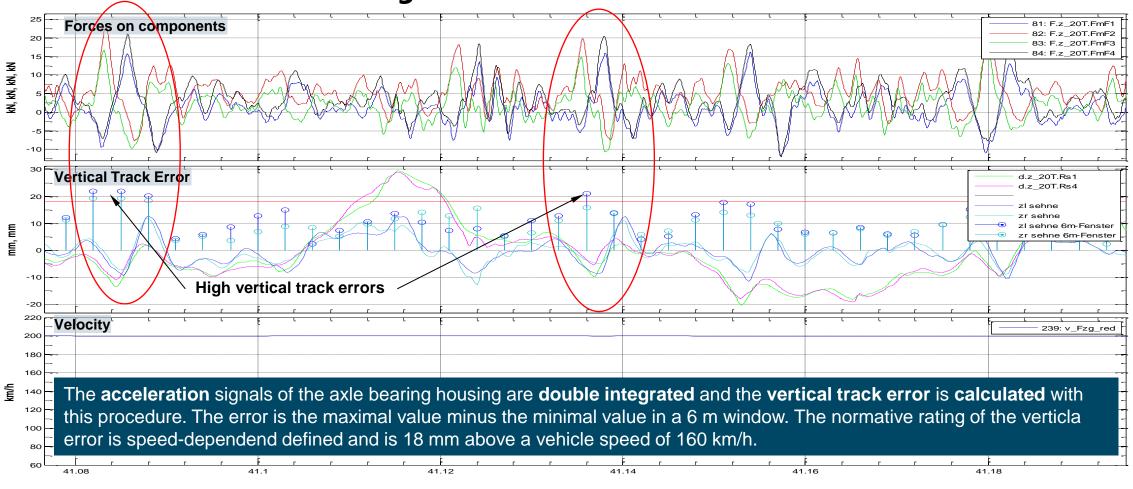
Seite 20 23.11.2016



High Speed Train: Track Geometry Analysis according to Forces on Components

**SIEMENS** 

## Vertical Track error according to the chord measurement



Open to Public © Siemens AG 2016



## High Speed Train: Track Geometry Analysis according to Forces on **Components**

SIEMENS

Soko

0

Vologda

oTutayev

Yaroslav

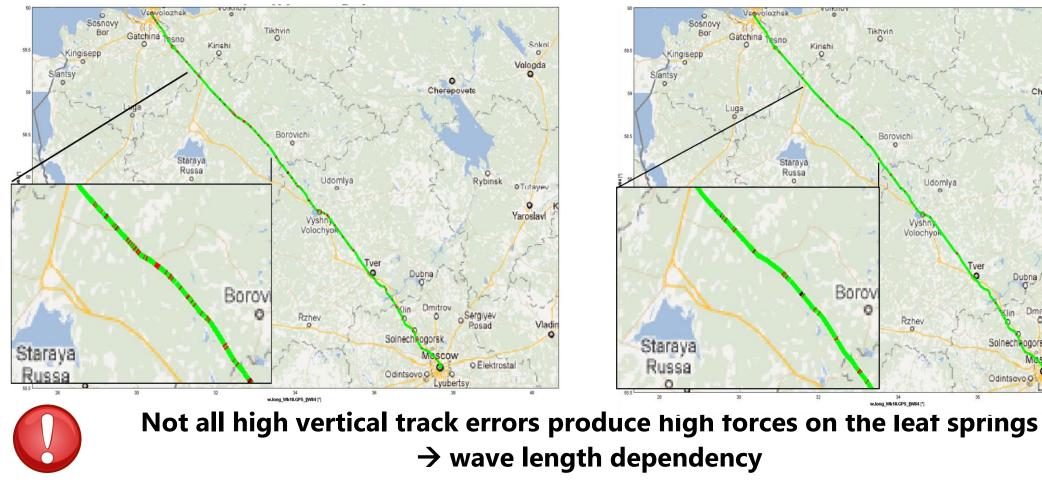
Cherepovets

Rybinsk

**Q**Elektrostal

Odintsovo O

## Vertical Track Error > 10mm



#### **High Forces on Component > 15 kN**

Kirishi

Staraya

Russa

Gatchina

Tikhvir

Borovich

Borov

Udomlya

Vysh

Voloch

Rzhev

w.long\_Wk10.GPS\_\$W84 [\*]

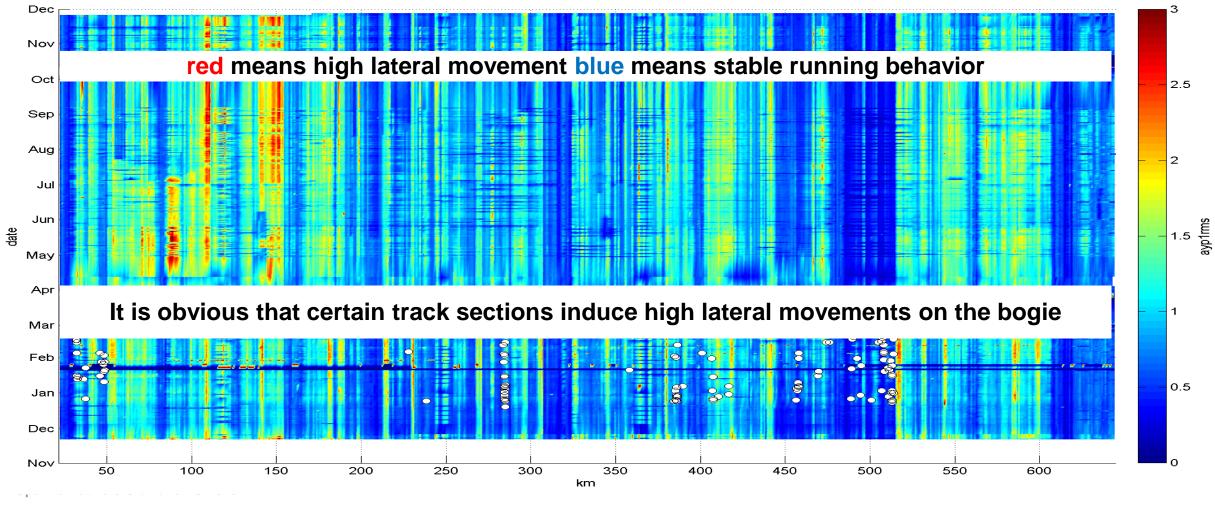
**Open to Public © Siemens AG 2016** 

Seite 22 23.11.2016





## Vehicle Reaction: Lateral Acceleration (1 year observation period)



23.11.2016



# What are the restrictions of the Vehicle-Track-Interaction Monitoring System?

**SIEMENS** 



Track Irregularities

Conicities



## **Restrictions:**

- Unstable running behavior is not only dependent on the track geometry, it is also influenced from
  - the wheel profile,
  - · the wheel guidance system and
  - the yaw damper functionality
- Therefore additional bogie diagnostics is essential to separate:
  - which reaction is coming from the worn bogie components
  - Which reaction is coming from the track irregularities
- **Different vehicles** might show **different reactions** on certain track defects (when should track maintenance efforts be started?)
- The SIEMENS Vehicle-Track-Interaction Monitoring System is not able to measure lateral track defects or track profiles but it measures the reactions of the vehicle on such defects which is essential for a save operation

Open to Public © Siemens AG 2016

Seite 24 23.11.2016



## Summary:

- SIEMENS has developed a **Bogie Diagnostics System** in order to **analyze** the **behavior of the bogie** over its lifetime in order to **optimize bogie maintenance efforts**.
- The same System is used to analyze the vehicle track interaction.
- Some characteristic parameters of the track such as longitudinal track levels are determined.
- In addition track faults e.g. **corrugations** are discovered.
- The difference of the vehicle track interaction system from track recording cars is that the **vehicle reactions induced by the track are measured and rated**.
- Analyzing the vehicle reactions over time in combination with the exact track position might lead to track maintenance works where the vehicle reactions are unfavourable (high forces and accelerations, instabilities, corrugations, worn switches).
- The main goal of the vehicle-track-interaction monitoring system is not to replace track recording cars but to give additional information about track sections where unfavourable vehicle reactions occur and thus might help to optimize track maintenance efforts.







**Dr. Thomas Moshammer** 

Head of Department Structure, Simulation, Validation Bogie Engineering

Siemens AG Österreich Eggenberger Strasse 31 8020 Graz

Tel.: +43 (51 707) 60 259 Mobile: +43 (664) 88 55 45 79

E-Mail: thomas.moshammer@siemens.com

siemens.com